



Natural Language Communication with Robots

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Components of Communication

Entity/Spatial Grounding

Understanding

. . . .

Planning and Plan Recognition

Language Generation

Grounding

The third block from the left



Understanding

place the nvidia block east of the hp block .



Plans



Draw the number six with a rigid base and a right diagonal top. Start with a line of 6 blocks in the middle of the table ...

Generation





[I need to] move UPS from the left side of the board to just below Starbucks, leaving a small gap.

Goal

Introduce a dataset collection paradigm for Human-Robot Communication: Understanding, Learning, and Generation

- 1. Easily evaluated
- 2. Data exists in 3D space
- 3. Natural language utterances
- 4. Parallel annotation at differing levels of abstraction
- 5. Computer Vision can help but is not a pre-requisite



Dataset

Action Sequences

Identifiable Sequences



Random Blank Sequences



Problem Solution Sequences



Long Seq

We focus on Single Actions in this work

Corpus Creation

Simple Actions



Move <u>HP</u> in front of <u>Twitter</u> and slightly to the left

Corpus Creation

Difficult Actions



Remove <u>the block above the right bottom block</u> and place it on top of <u>the left stack of blocks</u>.

Nine Annotations





1. coca cola , hp , nvidia .

- 2. nvidia, to the right of hp
- 3. place the nvidia block east of the hp block .
- 4. move the **nvidia** block to the **right** of the **hp** block
- 5. place the nvidia block to the east of the hp block .
- 6. move the **nvidia** block directly to the **right** of the **hp** block .
- move the nvidia block just to the right of the hp block in line with the mercedes block.
- put the nvidia block on the right end of the row of blocks that includes the coca cola and hp blocks.
- 9. put the **nvidia** block on the **same row as** the **coca cola** block, in the **first open space to the right** of the **coca cola** block.

Corpus Statistics

	Actions	Types	Tokens	Ave Len
MNIST	11,870	1,359	~257K	15 tokens
Random	2,492	1,172	~84K	23.5 tokens

Natural Language Understanding

Action Understanding

Given:

World Utterance

Goal: Execute a command



place the **nvidia** block east of the **hp** block .

Block to Move $(x, y, z)_S$

Where to Move $(x, y, z)_T$

World Representation

Images (w/ Occlusion)

Exact Locations



Adidas	0.8	0.1	0.76
BMW	-0.3	0.1	-0.4
Burger King	0.5	0.1	0.14
Coke	-0.07	0.1	0.00

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Evaluation: Euclidean Distance

Block to Move

$$||(x, y, z)_{SPred} - (x, y, z)_{SGold}||_2$$

Where to Move

 $||(x, y, z)_{TPred} - (x, y, z)_{TGold}||_2$

Baseline Models

Output:Block to MoveWhere to Move $(x, y, z)_S$ $(x, y, z)_T$

Random

Random Block to move Random Block to place it next to



Center

Perfect knowledge of which block to move Always place it in the center of the board



Simple Semantics

Model 1: A Discrete world (Source, Direction, Reference)



End-to-End Model

Move the BMW block in front of the Adidas block



 $(x, y, z)_{SPred}$

$$\label{eq:constraint} \begin{split} & \text{or} \\ & (x,y,z)_{TPred} \end{split}$$

End-to-End Model

Move the BMW block in front of the Adidas block

Assumed Logic: Can we encode this?



End-to-End Model



MNIST Performance

	Source	Target	
	Mean	Mean	
Human	0.00	0.53	
Simple Semantics	0.14	0.98	
End-To-End	0.19	1.05	
Center Baseline		3.43	
Random Baseline	6.49	6.21	

Blank Block Performance

	Source	Target
	Mean	Mean
Human	0.30	1.39
Simple Semantics	5.00	5.57
End-To-End	3.47	3.70
Center Baseline		4.06
Random Baseline	4.97	5.44

Common Errors

Multi-relation actions

Place block 20 parallel with the 8 block and slightly to the right of the 6 block.

Geometric Understanding

Continue the diagonal row of 20, 19 and 15 downward with 13.

Grammatical Ambiguity

19 moved from behind the 8 to under the 18th block.

Summary

This Work:

- Initial Models for Language Understanding
- An environment for exploring grounded phenomena

Moving Forward:

- Language Generation, Planning, ...
- Increased task difficulty.

Thanks!

http://nlg.isi.edu/language-grounding/